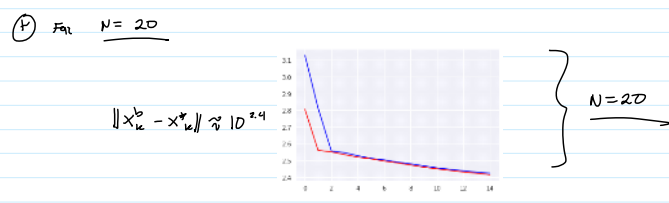
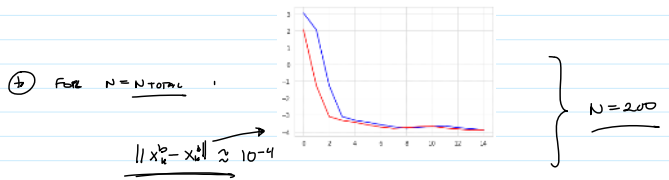
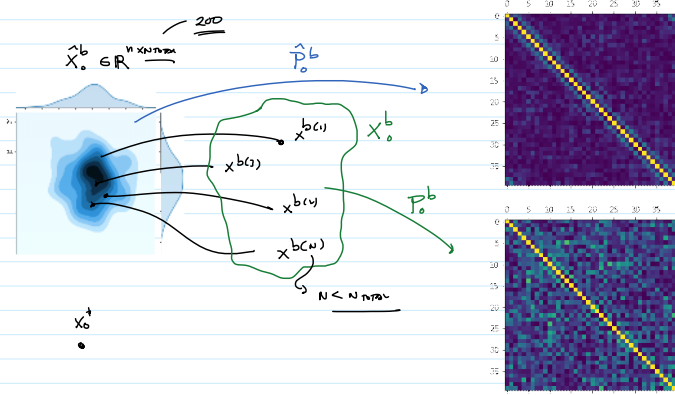
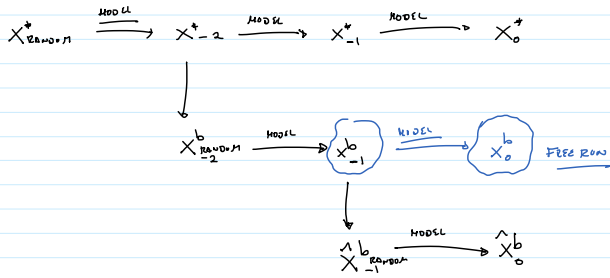


BENCHMARK



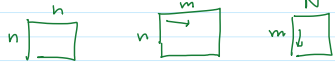
(+) SAMPLING CAN IMPACT THE QUALITY OF ANALYSIS CORRECTIONS (+) OJO

$R \in \mathbb{R}^{m \times m}$ $m \sim \mathcal{O}(10^6)$
 $X^a = X^b + P^b H^T (R + H P^b H^T)^{-1} D$ $D = y^c - H X^b$
 $P^b \in \mathbb{R}^{n \times n}$ $n \sim \mathcal{O}(10^8)$

LONG FLOAT COMPUTATIONS
 (+) (+)
 $X^a = X^b + P^b H^T Z$ $(R + H P^b H^T) Z = D$

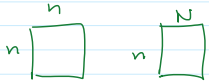
LONG FLOAT COMPUTATION

$$\textcircled{+} X^a = X^b + P^b H^T Z \quad (R + H P^b H^T) Z = D$$



$$\mathcal{O}(m^2)$$

$$\mathcal{O}(n^2 N + n m N) \quad \mathcal{O}(n m N) \quad \textcircled{+} \quad n \sim \mathcal{O}(10^8)$$



$$\mathcal{O}(n^2 N) \quad \text{DON'T BUY THAT S*$$

$$\textcircled{+} P^b = \frac{1}{N-1} \Delta X \Delta X^T \quad \Delta X \in \mathbb{R}^{n \times N}$$

$$\Delta X = \sum_{e=1}^{N-1} \sigma_e \cdot U_e \cdot V_e^T$$

$$P^b = \frac{1}{N-1} U \Sigma^2 U^T \quad \sigma_e > 0 \quad e < N$$

$\sigma_e = 0 \quad N \leq e < n$

RANK DEFICIENT

$$\Delta X = \begin{bmatrix} N & N & N \\ \vdots & \vdots & \vdots \\ N & N & N \end{bmatrix} \rightarrow P^b = \begin{bmatrix} N & N & N \\ \vdots & \vdots & \vdots \\ N & N & N \end{bmatrix} / N-1$$

$$\textcircled{+} X^a = X^b + P^b H^T Z \quad (R + H P^b H^T) Z = D$$

$$H P^b H^T = Q Q^T \quad Q = H \cdot \Delta X \frac{1}{\sqrt{N-1}} \quad \checkmark \in \mathbb{R}^{m \times N}$$

$$Q Q^T = \left[\frac{H \Delta X}{\sqrt{N-1}} \right] \left[\frac{H \Delta X}{\sqrt{N-1}} \right]^T$$

$$\hat{\Delta X} = \frac{1}{\sqrt{N-1}} \Delta X \in \mathbb{R}^{n \times N} = H \left(\frac{1}{N-1} \Delta X \Delta X^T \right) H^T = H P^b H^T$$

$$X^a = X^b + \hat{\Delta X} \hat{\Delta X}^T H^T Z$$

$$= X^b + \hat{\Delta X} (H \hat{\Delta X})^T Z$$

$$= X^b + \hat{\Delta X} Q^T Z \quad (R + H P^b H^T) Z = D$$

$$(R + Q Q^T) Z = D$$



$$\mathcal{O}(N^2 \cdot m) \quad \mathcal{O}(n \cdot N^2) \quad \mathcal{O}(N^2 \cdot m + N^2 \cdot n)$$

m AND n ARE LINEAR

```

DX_k = XB_k - np.outer(xb_k, np.ones(N));
DMS_k = 1/(np.sqrt(N-1))*DX_k;
# Innovation matrix
Q_k = H_k @ DMS_k;
TM_k = R_k + Q_k @ Q_k.T;
Z_k = np.linalg.solve(TM_k, D_k);
    
```

$$\textcircled{1} X^a = X^b + P^b H^T Z \rightarrow \mathcal{O}(N^2(n^2 + n m))$$

$$\textcircled{2} X^a = X^b + \hat{\Delta X} Q^T Z \rightarrow \mathcal{O}(N^2(m + n)) \quad \text{RANK-DEFICIENT}$$

$$\hat{\Delta X} = \frac{1}{\sqrt{N-1}} \Delta X \quad Q = H \hat{\Delta X} \in \mathbb{R}^{m \times N}$$

- O(N x N)

$$\hat{\Delta X} = \frac{1}{\sqrt{N-1}} \Delta X \quad Q = H \hat{\Delta X} \in \mathbb{R}^{M \times N}$$

$$\in \mathbb{R}^{N \times N}$$

$$X^a - X^b = \hat{\Delta X} \underbrace{Q^T Z}_{\Phi} \in \mathbb{R}^{N \times N}$$

$$X^a - X^b = \hat{\Delta X} \Phi \Rightarrow X^{a(e)} - X^{b(e)} = \hat{\Delta X} \cdot \phi^{(e)}$$

RANK

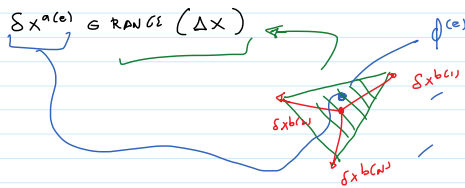
$$\Delta X^{a(e)} = \hat{\Delta X} \phi^{(e)}$$

$$\begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}$$

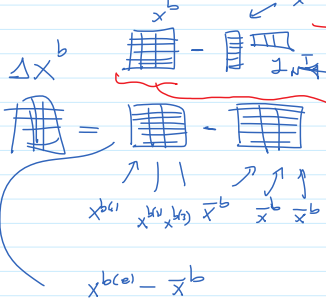
$$\Delta X^{a(e)} \in \text{SPAN} \left\{ \frac{1}{\sqrt{N-1}} \delta x^{b(1)}, \frac{1}{\sqrt{N-1}} \delta x^{b(2)}, \dots, \frac{1}{\sqrt{N-1}} \delta x^{b(N)} \right\}$$

$$\begin{bmatrix} 2 & 0 \\ 0 & 2 \end{bmatrix}$$

$$\in \text{RANGE}(\hat{\Delta X}) \sim \frac{1}{\sqrt{N-1}} \Delta X$$

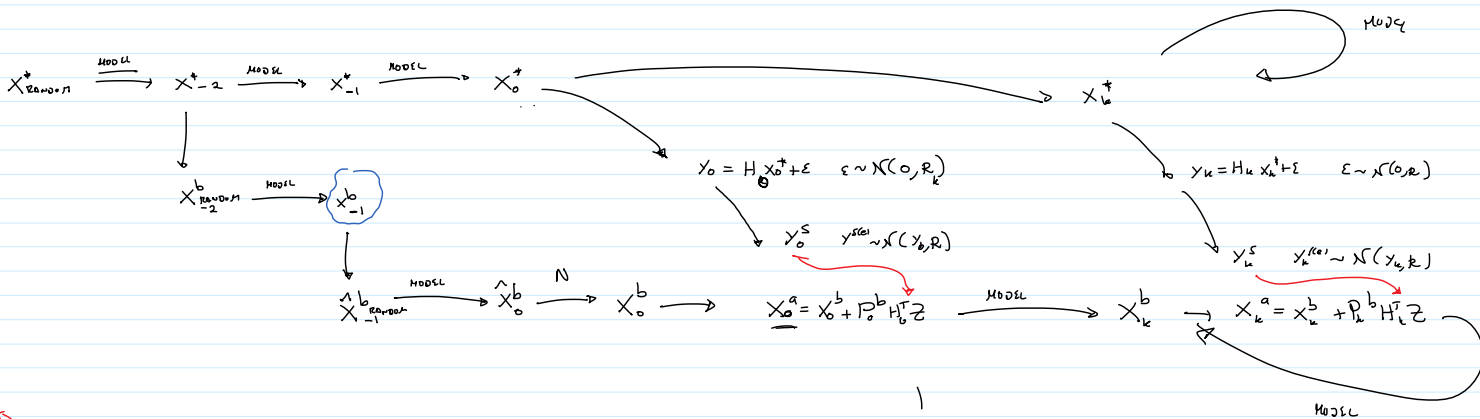


$$\textcircled{\oplus} \Delta X^b = X^b - \bar{x}^b \cdot \mathbf{1}_N^T$$



```
DX_k = XB_k - np.outer(xb_k, np.ones(N));
```

Benchmark



$\textcircled{\downarrow}$ LINEAR SYSTEM OF EQUATIONS

$$(R + H P^b H^T) Z = D$$

$$\textcircled{\downarrow} (R + Q Q^T) Z = D$$

$$\mathbb{E}(\epsilon \epsilon^T) = 0$$

$$R + H P^b H^T = (R^b + H \hat{\Delta X}^b) (R^b + H \hat{\Delta X}^b)^T$$

$$y \sim N(\mu, \Sigma)$$

$$\mathbb{E}(\varepsilon_i \varepsilon_i^T) = 0$$

$$R + H P^b H^T = (R^{1/2} + H \Delta X^b) (R^{1/2} + H \Delta X^b)^T$$

$\eta \sim \mathcal{N}(0, I)$
 $\beta \eta \sim \mathcal{N}(0, B B^T)$

$$\mathbb{E}(\varepsilon_1 \varepsilon_1^T) = 0 \quad \text{cov}(\varepsilon_1, \varepsilon_2) = 0 \in \mathbb{R}^{m \times n}$$

$$\varepsilon_1 \sim \mathcal{N}(0, \Sigma_m)$$

$$\varepsilon_2 \sim \mathcal{N}(0, \Sigma_n)$$

$$R^{1/2} \varepsilon_1 \sim \mathcal{N}(0, R)$$

$$H \Delta X^b \varepsilon_2 \sim \mathcal{N}(0, H \Delta X^b \Delta X^{bT} H^T)$$

$$H \Delta X^b \varepsilon_2 \sim \mathcal{N}(0, H P^b H^T)$$

$$\mathbb{E}([R^{1/2} \varepsilon_1 + H \Delta X^b \varepsilon_2][R^{1/2} \varepsilon_1 + H \Delta X^b \varepsilon_2]^T) \quad \text{⊕ MANDEL}$$

$$= \mathbb{E}(R^{1/2} \varepsilon_1 \varepsilon_1^T R^{1/2} + R^{1/2} \varepsilon_1 \varepsilon_2^T \Delta X^b H^T + H \Delta X^b \varepsilon_2 \varepsilon_1^T R^{1/2} + H \Delta X^b \varepsilon_2 \varepsilon_2^T \Delta X^{bT} H^T)$$

$$= R^{1/2} \mathbb{E}(\varepsilon_1 \varepsilon_1^T) R^{1/2} + R^{1/2} \mathbb{E}(\varepsilon_1 \varepsilon_2^T) \Delta X^b H^T + H \Delta X^b \mathbb{E}(\varepsilon_2 \varepsilon_1^T) R^{1/2} + H \Delta X^b \mathbb{E}(\varepsilon_2 \varepsilon_2^T) \Delta X^{bT} H^T$$

$$= R + H \Delta X^b \Delta X^{bT} H^T = R + H P^b H^T \quad \checkmark OK$$

$$\text{⊕} \quad R + H \Delta X^b = U \Sigma^T V^T \quad \begin{matrix} m & n \\ \square & \square \end{matrix} = U \Sigma^T V^T$$

$$R + H P^b H^T = U \Sigma^T V^T V \Sigma U^T = U \Sigma^2 U^T$$

$$(R + H P^b H^T) z = D \Rightarrow [U \Sigma^2 U^T] z = D$$

DAGONAL
ORTHOGONALS

$$z = U \Sigma^{-2} U^T D$$

$$U U^T = U^T U = I$$

$$\text{⊕} \quad \underline{\underline{SVP}} \quad \begin{matrix} n \\ \square \end{matrix} \quad n \gg n \quad \theta(N^2 n) \rightarrow \text{LINEAR} \neq \text{VAR} = \text{QR FACTORIZATION}$$

$$\begin{matrix} m \\ \square \end{matrix} \quad \theta(m^2) \quad ?$$

$$\begin{matrix} m & n \\ \square & \square \end{matrix} + \begin{matrix} n \\ \square \end{matrix} = U \Sigma^T V^T \quad \underline{\underline{STAT}}$$

$$\text{⊕} \quad \underline{\underline{SVP}} \quad (R + Q Q^T) z = D$$

$$Q \in \mathbb{R}^{m \times n} \quad Q = H \Delta X^b \quad \Delta X^b = \frac{1}{\|\cdot\|} \Delta X^b$$

$$Q \in \mathbb{R}^{m \times N} \quad Q = H \hat{\Delta X}^b \quad \hat{\Delta X}^b = \frac{1}{\sqrt{N-1}} \Delta X^b$$

$$Q = U \Sigma^T V^T \Rightarrow \Theta(m \cdot N^2) \Rightarrow \Delta X^b = X^b - \bar{x}^b \mathbf{1}_N^T$$

$\underbrace{\hspace{10em}}_{\text{LINEAR IN REGARD TO } \# \text{ OBS}}$



$$\textcircled{2} \quad R + Q Q^T = R + (U \Sigma^T V^T)(U \Sigma^T V^T)^T = R + U \Sigma^2 U^T$$

$N(0, \sigma^2)$

- ① R IS DIAGONAL
- ② R IS BLOCK-DIAGONAL
- ③ R IS EASY TO DECOMPOSE

$$\hookrightarrow R = \sigma^2 I$$

$$R + Q Q^T = \sigma^2 I + U \Sigma^2 U^T = U [\sigma^2 I + \Sigma^2] U^T$$

$\underbrace{\sigma^2 I}_{\text{ORTHOGONAL}} + \underbrace{\Sigma^2}_{\text{DIAGONAL}} \rightarrow \text{ORTHOGONAL}$

$$= \begin{matrix} N & & m \\ \boxed{U} & \boxed{\hat{\Sigma}^2} & \boxed{U^T} \\ m & N & N \end{matrix} = \underline{\underline{R + H P^b H^T}}$$

$$\mathcal{L}[R + H P^b H^T] z = D \Rightarrow U \hat{\Sigma}^2 U^T z = D$$

$$\boxed{z = U \hat{\Sigma}^{-2} U^T D}$$

$$\textcircled{3} \quad x^a = x^b + \hat{\Delta X}^b Q^T z$$

$$= x^b + \hat{\Delta X}^b [U \Sigma^T V^T]^T [U \hat{\Sigma}^{-2} U^T D]$$

$$= x^b + \hat{\Delta X}^b \underbrace{V \Sigma U^T U}_{I} \hat{\Sigma}^{-2} U^T D$$

$$= x^b + \hat{\Delta X}^b \sqrt{\Sigma} \hat{\Sigma}^{-2} U^T D \rightarrow (\sigma^2 I + \Sigma^2)^{-2}$$

$$= x^b + \hat{\Delta X}^b \sqrt{\cdot} \text{diag} \left(\frac{\sigma_i}{\sigma_i^2 + \sigma^2} \right) U^T D$$

